

Comment on 'Conservative discretizations of the Kepler motion'

This article has been downloaded from IOPscience. Please scroll down to see the full text article.

2010 J. Phys. A: Math. Theor. 43 228001

(<http://iopscience.iop.org/1751-8121/43/22/228001>)

View [the table of contents for this issue](#), or go to the [journal homepage](#) for more

Download details:

IP Address: 171.66.16.159

The article was downloaded on 03/06/2010 at 09:17

Please note that [terms and conditions apply](#).

COMMENTS AND REPLIES

Comment on ‘Conservative discretizations of the Kepler motion’

Jan L Cieřliński

Uniwersytet w Białymstoku, Wydział Fizyki, ul. Lipowa 41, 15-424 Białystok, Poland

E-mail: janek@alpha.uwb.edu.pl

Received 27 November 2009

Published 11 May 2010

Online at stacks.iop.org/JPhysA/43/228001

Abstract

We show that the exact integrator for the classical Kepler motion, recently found by Kozlov (2007 *J. Phys. A: Math. Theor.* **40** 4529–39), can be derived in a simple natural way, using a well-known exact discretization of the harmonic oscillator. We also draw attention to important earlier references, where the exact discretization of the four-dimensional isotropic harmonic oscillator has been applied to the perturbed Kepler problem.

PACS numbers: 45.10.–b, 45.50.Pk, 02.70.Bf, 02.60.Cb, 02.30.Hq, 02.30.Ik

Mathematics Subject Classification: 65P10, 65L12, 34K28

In recent years several conservative discretizations of the classical Kepler problem have been proposed [1–5]. These numerical integrators preserve all integrals of motion and trajectories but only Kozlov’s schemes are of order higher than 2. Kozlov also found the exact integrator by guessing its proper form and summing up some infinite series [4].

In this comment we show that Kozlov’s exact integrator can be derived in a simple elementary way. Conservative discretizations of the three-dimensional Kepler motion obtained in [3, 4] consist in applying the midpoint rule (or the discrete gradient method, compare [6]) to the isotropic four-dimensional harmonic oscillator equations:

$$\frac{d\mathbf{Q}}{ds} = \frac{1}{4}\mathbf{P}, \quad \frac{d\mathbf{P}}{ds} = 2E\mathbf{Q} \quad (\mathbf{Q}, \mathbf{P} \in \mathbb{R}^4) \quad (1)$$

where $E = \text{const}$ is the energy integral of the considered Kepler motion. Then, the authors of [3, 4] use the Kustaanheimo–Stiefel (KS) transformation. This classical transformation is given by ([7], see also [4])

$$\mathbf{q} = \begin{pmatrix} Q_1^2 - Q_2^2 - Q_3^2 + Q_4^2 \\ 2Q_1Q_2 - 2Q_3Q_4 \\ 2Q_1Q_3 + 2Q_2Q_4 \end{pmatrix}, \quad (2)$$

$$\mathbf{p} = \frac{1}{2|\mathbf{Q}|^2} \begin{pmatrix} P_1Q_1 - P_2Q_2 - P_3Q_3 + P_4Q_4 \\ P_1Q_2 + P_2Q_1 - P_3Q_4 - P_4Q_3 \\ P_1Q_3 + P_2Q_4 + P_3Q_1 + P_4Q_2 \end{pmatrix}, \quad (3)$$

where \mathbf{Q}, \mathbf{P} are subject to the constraint

$$P_1 Q_4 - P_2 Q_3 + P_3 Q_2 - P_4 Q_1 = 0. \tag{4}$$

The KS transformation, together with the Lévi-Civita time transformation

$$\frac{dt}{ds} = |\mathbf{q}| \tag{5}$$

maps the four-dimensional harmonic oscillator (1) into the three-dimensional Kepler problem equations:

$$\frac{d\mathbf{q}}{dt} = \mathbf{p}, \quad \frac{d\mathbf{p}}{dt} = -\frac{k\mathbf{q}}{|\mathbf{q}|^3} \quad (\mathbf{q}, \mathbf{p} \in \mathbb{R}^3), \tag{6}$$

where $k = \text{const}$. Using (2), (3) and (4) we can verify the useful identities

$$|\mathbf{q}|^2 = |\mathbf{Q}|^4, \quad |\mathbf{P}|^2 = 4|\mathbf{p}|^2|\mathbf{Q}|^2, \tag{7}$$

which imply the equivalence of the energy conservation laws:

$$\frac{1}{2}\mathbf{p}^2 - \frac{k}{|\mathbf{q}|} = E \iff \frac{1}{8}|\mathbf{P}|^2 - E|\mathbf{Q}|^2 = k. \tag{8}$$

The phenomenon of interchanging coupling constants with integrals of motion (like $k \leftrightarrow E$) is quite well known in the theory of integrable systems, see [8] (compare also [9], where more general results can be found).

In order to derive Kozlov’s numerical results in a simple straightforward way it is sufficient to note that the KS transformation (used by Kozlov) reduces the Kepler motion to linear ordinary differential equations with constant coefficients (namely to the harmonic oscillator) and for all such equations there exist explicit exact numerical integrators ([10, 11], see also [12]). By the exact discretization of an ordinary differential equation $\dot{x} = f(x)$, where $x(t) \in \mathbb{R}^N$, we mean the one-step numerical scheme of the form $X_{n+1} = \Phi_h(X_n)$, such that $X_n = x(t_n)$, compare [10, 11].

The system (1), equivalent to the four-dimensional harmonic oscillator equation, admits the exact discretization (see, for instance, [12]):

$$\begin{aligned} \frac{\mathbf{Q}_{j+1} - \mathbf{Q}_j}{\delta(h_j)} &= \frac{1}{4} \frac{\mathbf{P}_{j+1} + \mathbf{P}_j}{2}, \\ \frac{\mathbf{P}_{j+1} - \mathbf{P}_j}{\delta(h_j)} &= 2E \frac{\mathbf{Q}_{j+1} + \mathbf{Q}_j}{2}, \end{aligned} \tag{9}$$

where $h_j := s_{j+1} - s_j$ is the (variable) s -step, $\mathbf{Q}_j, \mathbf{P}_j$ denote j th iteration of the numerical scheme (not to be confused with the coordinates Q_j, P_j) and

$$\delta(h_j) = \frac{2}{\omega} \tan \frac{\omega h_j}{2}, \quad \omega^2 = -\frac{1}{2}E. \tag{10}$$

In the case of the constant step $h_j = h$ and $E < 0$, we recognize here the exact integrator found by Kozlov (see formulae (4.11) and (4.14) from [4], taking into account that $\delta(h) = ha(h) = hb(h)$ and $E = -A$). The hyperbolic and parabolic cases (formulae (4.16) and (4.18) from [4]) follow immediately when we take imaginary ω (i.e. $E > 0$) or $\omega = 0$. The exact numerical scheme (9) preserves the energy integral, i.e.

$$\frac{1}{8}|\mathbf{P}_j|^2 - E|\mathbf{Q}_j|^2 = k. \tag{11}$$

Note that the system (9) can be rewritten in the explicit form:

$$\begin{aligned} \mathbf{Q}_{j+1} &= \cos \omega h_j \mathbf{Q}_j + \frac{\sin \omega h_j}{4\omega} \mathbf{P}_j, \\ \mathbf{P}_{j+1} &= -4\omega \sin \omega h_j \mathbf{Q}_j + \cos \omega h_j \mathbf{P}_j. \end{aligned} \tag{12}$$

This system is a direct consequence of evaluating the exact solution of (1) at $s = s_j$ and $s = s_j + h_j$, compare [12].

Equation (5) can be solved exactly in different (but more or less equivalent) ways, compare [4, 13, 14]. Here we propose one more approach, reducing this problem to linear ordinary differential equations with constant coefficients. If \mathbf{Q}, \mathbf{P} satisfy (1) and t satisfies (5), then we easily check that

$$\frac{d\mathbf{w}}{ds} = \Omega\mathbf{w}, \quad \mathbf{w} = \begin{pmatrix} |\mathbf{Q}|^2 \\ |\mathbf{P}|^2 \\ \mathbf{Q} \cdot \mathbf{P} \\ t \end{pmatrix}, \quad \Omega = \begin{pmatrix} 0 & 0 & \frac{1}{2} & 0 \\ 0 & 0 & 4E & 0 \\ 2E & \frac{1}{4} & 0 & 0 \\ 1 & 0 & 0 & 0 \end{pmatrix}. \quad (13)$$

In such a case we can proceed in a standard way. The general solution is given by $\mathbf{w}(s) = \exp(s\Omega)\mathbf{w}(0)$. Therefore, the exact discretization, $\mathbf{w}_n = \mathbf{w}(hn)$, satisfies

$$\mathbf{w}_{n+1} = \exp(h\Omega)\mathbf{w}_n, \quad (14)$$

and the problem reduces to the well-known, purely algebraic procedure of computing $e^{\Omega h}$. In our particular case we observe that $\Omega^4 = 2E\Omega^2$ which simplifies computations. The last row in equation (14) reads

$$t_{j+1} = t_j + \frac{\sin 2h\omega}{4\omega} \left(|\mathbf{Q}_j|^2 - \frac{|\mathbf{P}_j|^2}{16\omega^2} \right) + \frac{h}{2} \left(|\mathbf{Q}_j|^2 + \frac{|\mathbf{P}_j|^2}{16\omega^2} \right) + \frac{\mathbf{Q}_j \cdot \mathbf{P}_j \sin^2 h\omega}{4\omega^2}. \quad (15)$$

One can check by direct computation that discretization (15), although has a simpler form, is identical with formulae (4.11), (4.15) of [4]. Finally, eliminating $|\mathbf{P}_j|^2$ by virtue of (11), we get

$$t_{j+1} = t_j + \frac{hk}{4\omega^2} \left(1 - \frac{\sin 2h\omega}{2h\omega} \right) + \frac{\sin 2h\omega}{2\omega} |\mathbf{Q}_j|^2 + \frac{\mathbf{Q}_j \cdot \mathbf{P}_j \sin^2 h\omega}{4\omega^2}. \quad (16)$$

Another approach (see [13]) consists in computing the integral $\int |\mathbf{Q}(s)|^2 ds$, where \mathbf{Q} is the exact solution of (1). Formula (86) from [13] is identical to (16) (although notation is quite different).

In celestial mechanics the exact discretization of the Kepler motion via the KS transformation appeared as a quite natural step [13–15], although the conservative properties of the exact integrator are not discussed explicitly in these papers. Long ago Stiefel and Bettis, working in the framework of the Gautschi approach [17], applied the exact discretization of the harmonic oscillator to the perturbed Kepler motion [15, 16].

More recently, Mikkola [13] and Breiter [14] proposed new integrators for the perturbed Kepler problem, using the exact solution of the four-dimensional isotropic harmonic oscillator equation and the exact discretization (16) of the time (known to Stumpff even before the KS transform was invented, compare [13]). In particular, the numerical scheme (12) can be found in [13], p 162, and in [14], p 234. Breiter follows [18] using an additional constant in the definition of the KS transformation (in fact scaling both \mathbf{q} and \mathbf{p}). The freedom of choosing this parameter can be used to fix the value of ω (e.g. $\omega = 1$) which may have numerical advantages [14].

These important results of celestial mechanics are not mentioned in [4] and, in general, they seem to be rather unknown in the field of geometric numerical integration [19]. It is worthwhile to mention that the exact discretization of the harmonic oscillator equation has been recently used to construct new geometric integrators of high accuracy ('locally exact discrete gradient schemes') [12, 20]. We plan to apply this scheme to the perturbed Kepler problem using the Kustaanheimo–Stiefel map.

References

- [1] Quispel G R W and Dyt C 1997 Solving ODE's numerically while preserving symmetries, Hamiltonian structure, phase space volume, or first integrals *Proc. 15th IMACS World Congress* vol 2, ed A Sydow (Berlin: Wissenschaft & Technik Verlag) pp 601–7
- [2] Minesaki Y and Nakamura Y 2002 A new discretization of the Kepler motion which conserves the Runge-Lenz vector *Phys. Lett. A* **306** 127–33
- [3] Minesaki Y and Nakamura Y 2004 A new conservative numerical integration algorithm for the three-dimensional Kepler motion based on the Kustaanheimo–Stiefel regularization theory *Phys. Lett. A* **324** 282–92
- [4] Kozlov R 2007 Conservative discretizations of the Kepler motions *J. Phys. A: Math. Theor.* **40** 4529–39
- [5] Cieřliński J L 2007 An orbit-preserving discretization of the classical Kepler problem *Phys. Lett. A* **370** 8–12
- [6] LaBudde R A and Greenspan D 1974 Discrete mechanics—a general treatment *J. Comput. Phys.* **15** 134–67
- [7] Kustaanheimo P and Stiefel E 1965 Perturbation theory of Kepler motion based on spinor regularization *J. Reine Angew. Math.* **218** 204–19
- [8] Hietarinta J, Grammaticos B, Dorizzi B and Ramani A 1984 Coupling-constant metamorphosis and duality between integrable Hamiltonian systems *Phys. Rev. Lett.* **53** 1707–10
- [9] Sergyeyev A and Błaszak M 2008 Generalized Stäckel transform and reciprocal transformation for finite-dimensional integrable systems *J. Phys. A: Math. Theor.* **41** 105205
- [9] Kalnins E G, Miller W Jr and Post S 2010 Coupling constant metamorphosis and N th-order symmetries in classical and quantum mechanics *J. Phys. A: Math. Theor.* **43** 035202
- [10] Potts R B 1982 Differential and difference equations *Am. Math. Mon.* **89** 402–7
- [11] Agarwal R P 2000 *Difference Equations and Inequalities* (New York: Dekker) chapter 3
- [12] Cieřliński J L 2010 On the exact discretization of the classical harmonic oscillator equation *J. Diff. Eqns Appl.* arXiv:0911.3672v1 [math-ph] at press
- [13] Mikkola S 1997 Practical symplectic methods with time transformations for the few-body problem *Celestial Mech. Dyn. Astron.* **67** 145–65
- [14] Breiter S 1999 Explicit symplectic integrator for highly eccentric orbits *Celest. Mech. Dyn. Astron.* **71** 229–41
- [15] Stiefel E and Bettis D G 1969 Stabilization of Cowell's method *Numer. Math.* **13** 154–75
- [16] Bettis D G 1970 Stabilization of finite difference methods of numerical integration *Celest. Mech.* **2** 282–95
- [17] Gautschi W 1961 Numerical integration of ordinary differential equations based on trigonometric polynomials *Numer. Math.* **3** 381–97
- [18] Deprit A, Elpe A and Ferrer S 1994 Linearization: Laplace vs. Stiefel *Celest. Mech. Dyn. Astron.* **58** 151–201
- [19] Hairer E, Lubich C and Wanner G 2006 *Geometric Numerical Integration: Structure-Preserving Algorithms for Ordinary Differential Equations* 2nd edn (Berlin: Springer)
- [20] Cieřliński J L and Ratkiewicz B 2009 How to improve the accuracy of the discrete gradient method in the one-dimensional case arXiv:0901.1906v1 [cs.NA]
- [20] Cieřliński J L and Ratkiewicz B 2010 Improving the accuracy of the discrete gradient method in the one-dimensional case *Phys. Rev. E* **81** 016704